

$$1) \quad \bar{A} = \frac{d}{dt} \bar{V}$$

$$= \frac{d}{dt} \bar{V} + \bar{\omega}^{bi} \times \bar{V}$$

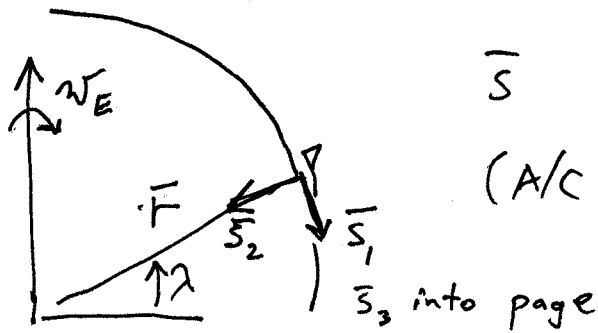
$$\bar{\omega}^{bi} = \dot{\gamma} \bar{b}_3$$

$$\bar{V} = v \bar{b}_1 \implies \frac{d}{dt} \bar{V} = \dot{v} \bar{b}_1$$

$$\bar{A} = \dot{v} \bar{b}_1 + \dot{\gamma} \bar{b}_3 \times v \bar{b}_1$$

$$\bar{A} = \dot{v} \bar{b}_1 + v \dot{\gamma} \bar{b}_2$$

2)

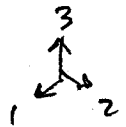


$\bar{s}$  is Earth fixed  
(A/C flying past)

$$\text{Coriolis accel} = \bar{a} = 2 \bar{\omega}^{si} \times \frac{d}{dt} \bar{r}$$

$$\bar{\omega}^{si} = \omega_E (-\bar{s}_1 \cos \lambda - \bar{s}_2 \sin \lambda)$$

$$\frac{d}{dt} \bar{r} = V \bar{s}_1$$



$$\bar{a} = 2(-\omega_E \sin \lambda \bar{s}_2) \times V \bar{s}_1$$

$$= 2 \omega_E \sin \lambda V \bar{s}_3$$

$$\bar{a} = 2 \omega_E \sin \lambda V \bar{s}_3$$

(East)

if regarded as a force, we  
would be pushed to the right  
in the northern hemisphere, left  
in the southern

3) 1.6)

$$\vec{F} = x\vec{s}_1 + y\vec{s}_2$$

$$\dot{\omega} = 0$$

$$\frac{\vec{F}}{m} = \frac{d^2}{dt^2} \vec{r} = \frac{d^2}{dt^2} \vec{r} + 2\vec{\omega}^{si} \times \frac{d}{dt} \vec{r} + \vec{\omega}^{si} \times (\vec{\omega}^{si} \times \vec{r})$$

$$\frac{\vec{F}}{m} = (\ddot{x}\vec{s}_1 + \ddot{y}\vec{s}_2) + 2(\omega\vec{s}_3) \times (\dot{x}\vec{s}_1 + \dot{y}\vec{s}_2) + (\omega\vec{s}_3) \times (\omega\vec{s}_3 \times (x\vec{s}_1 + y\vec{s}_2))$$

$$\begin{aligned} \frac{\vec{F}}{m} &= \ddot{x}\vec{s}_1 + \ddot{y}\vec{s}_2 \\ &+ (-2\omega\dot{y}\vec{s}_1 + 2\omega\dot{x}\vec{s}_2) \\ &+ (-\omega^2 x\vec{s}_1 - \omega^2 y\vec{s}_2) \end{aligned}$$

$$\vec{F} \cdot \vec{s}_1 = m(\ddot{x} - 2\omega\dot{y} - \omega^2 x)$$

$$\vec{F} \cdot \vec{s}_2 = m(\ddot{y} + 2\omega\dot{x} - \omega^2 y)$$

fall:  $\vec{F} = 0$

initially,  $y=0, x>0, \dot{y}=0, \dot{x}>0$

$$\ddot{y} + 2\omega\dot{x} - \omega^2 y = 0$$

$$\ddot{y} = \underbrace{-2\omega\dot{x}}_{<0} + \underbrace{\omega^2 y}_{\text{initially small}}$$

$\therefore y$  becomes ~~negative~~ negative

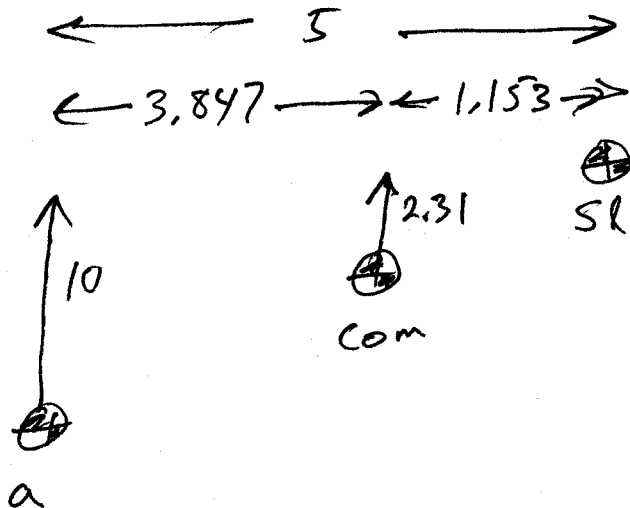
put ladder on "left" side ( $-\vec{s}_2$ )

4) (a)

$$\bar{V}_{com} = \frac{1}{m_a + m_{sl}} (m_a \bar{V}_a + m_{sl} \bar{V}_{sl}) =$$

$$= \frac{m_a}{m_a + m_{sl}} \bar{V}_a = 2.307 \bar{b}_2 \frac{m}{s}$$

(b)



$$\bar{V}_{sl} \text{ w/r/t com} = -2.31 \bar{b}_2 \frac{m}{s}$$

$$\bar{V}_a \text{ w/r/t com} = 7.693 \frac{m}{s} \bar{b}_2$$

$$\bar{H} = \sum_{i=1}^2 m_i \bar{r}_i \times \bar{V}_i$$

$$= -15000 \cdot 3.846 \cdot 7.693 \bar{b}_3$$

$$+ -50000 \cdot 1.157 \cdot 2.307 \bar{b}_3$$

$$= -5.772 \times 10^5 \frac{kgm^2}{sec} \bar{b}_3$$

(c) Parallel Axis Theorem

$$I = I_{sl} + m_{sl} \begin{bmatrix} \Delta y^2 + \Delta z^2 & -\Delta x \Delta y & \vdots \\ \vdots & \vdots & \vdots \end{bmatrix} \\ + I_a + m_a \begin{bmatrix} \Delta y^2 + \Delta z^2 & -\Delta x \Delta y & \vdots \\ \vdots & \vdots & \vdots \end{bmatrix}$$

$$I = I_{sl} + 50000 \begin{bmatrix} .8519 & -1.065 & 0 \\ -1.065 & 1.331 & 0 \\ 0 & 0 & 2.183 \end{bmatrix}$$

$$+ I_A + \begin{bmatrix} 142 & -177.53 & 0 \\ -177.53 & 221.87 & 0 \\ 0 & 0 & 363.94 \end{bmatrix} \times 10^3$$

$$I = \begin{bmatrix} 294.59 & -230.77 & 0 \\ -230.77 & 350.42 & 0 \\ 0 & 0 & 543.12 \end{bmatrix} \times 10^3 \text{ kgm}^2$$

(d)  $\bar{b}_3$  is a principle axis  
of docked config, and  
 $\bar{H}$  is in this direction

$$\therefore \omega_1 = \omega_2 = 0$$

$$\omega_3 I_z \bar{b}_3 = \bar{H} = 5.772 \times 10^5 \frac{\text{kgm}^2}{\text{sec}}$$

$$|\omega_3| = \frac{|\bar{H}|}{I_z} = 1.062 \frac{\text{rad}}{\text{sec}}$$

$$\omega_3 = -1.062 \frac{\text{rad}}{\text{sec}}$$

Note: It can be shown  
this is a rotation about  
the intermediate moment of inertia  
 $\therefore$  unstable!